



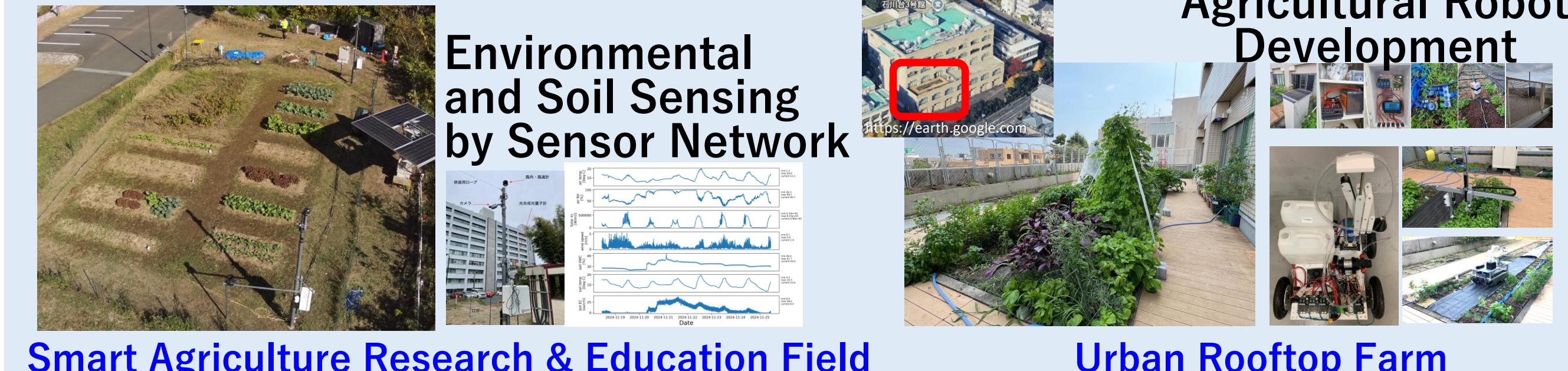
Research Outline

Our laboratory promotes **Smart Agriculture** through a comprehensive framework integrating **mechanical systems**, **robotics**, **sensing**, and **AI**:

- **Off-grid Energy & Communication**: Providing stable power, water supply, and telecommunications to remote agricultural sites.
- **Sensing**: Monitoring temperature, humidity, light intensity, pH, plant growth, and other key variables.
- **Actuation**: Automating soil and crop management (e.g., pruning and harvesting), including **automated robotic systems for tomato lower-leaf processing** and **wildlife-damage prevention device** development.
- **Ecosystem-based Organic Agriculture**: Advancing sustainable, organic farming that leverages biodiversity.

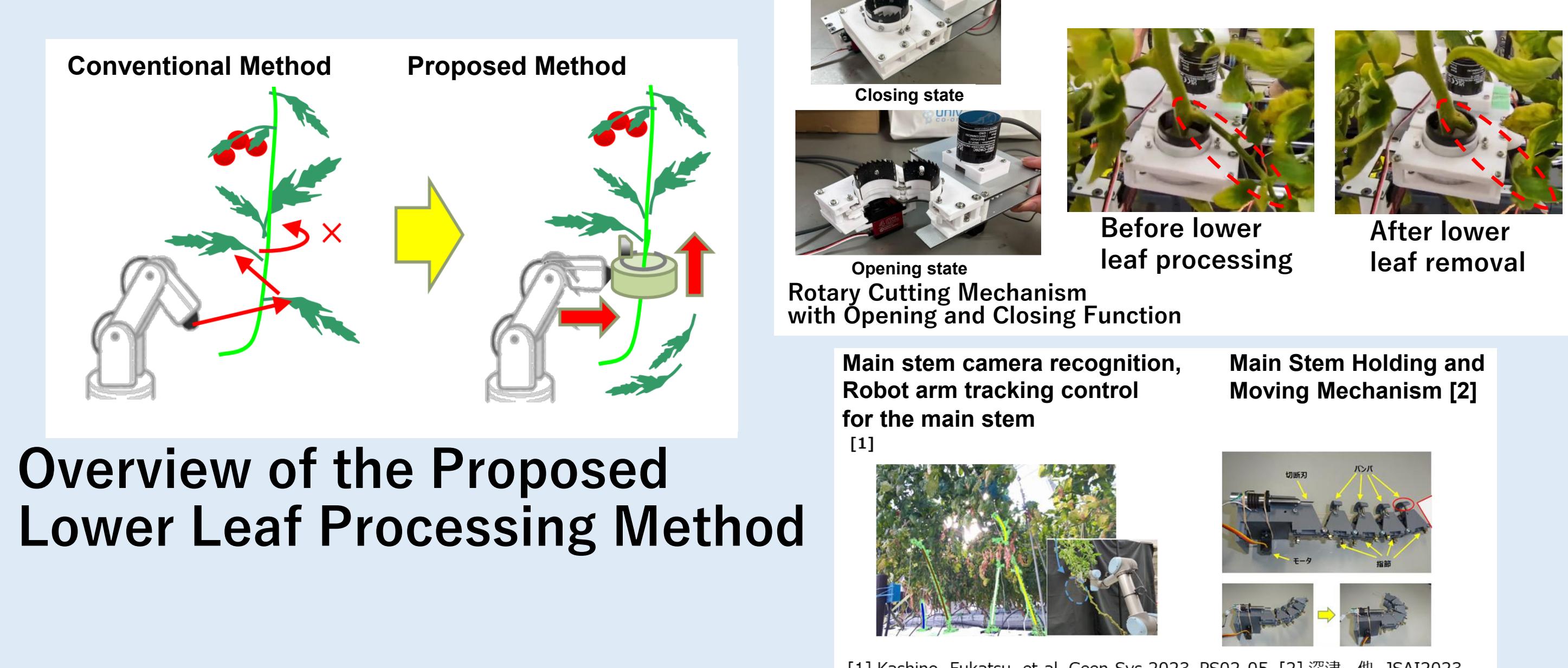
Digital Twin: The core platform integrating these technologies—visualizing field data from robots, sensor networks, and **smart agricultural boots** for environmental mapping—and delivering real-time predictions for optimal cultivation strategies.

Through integrated **research and education**, we shape the future of socially implemented, inclusive agriculture and help realize a **sustainable, productive, and inclusive Super Smart Society**.



Development of an Automated Robot System for Lower Leaf Processing Operations

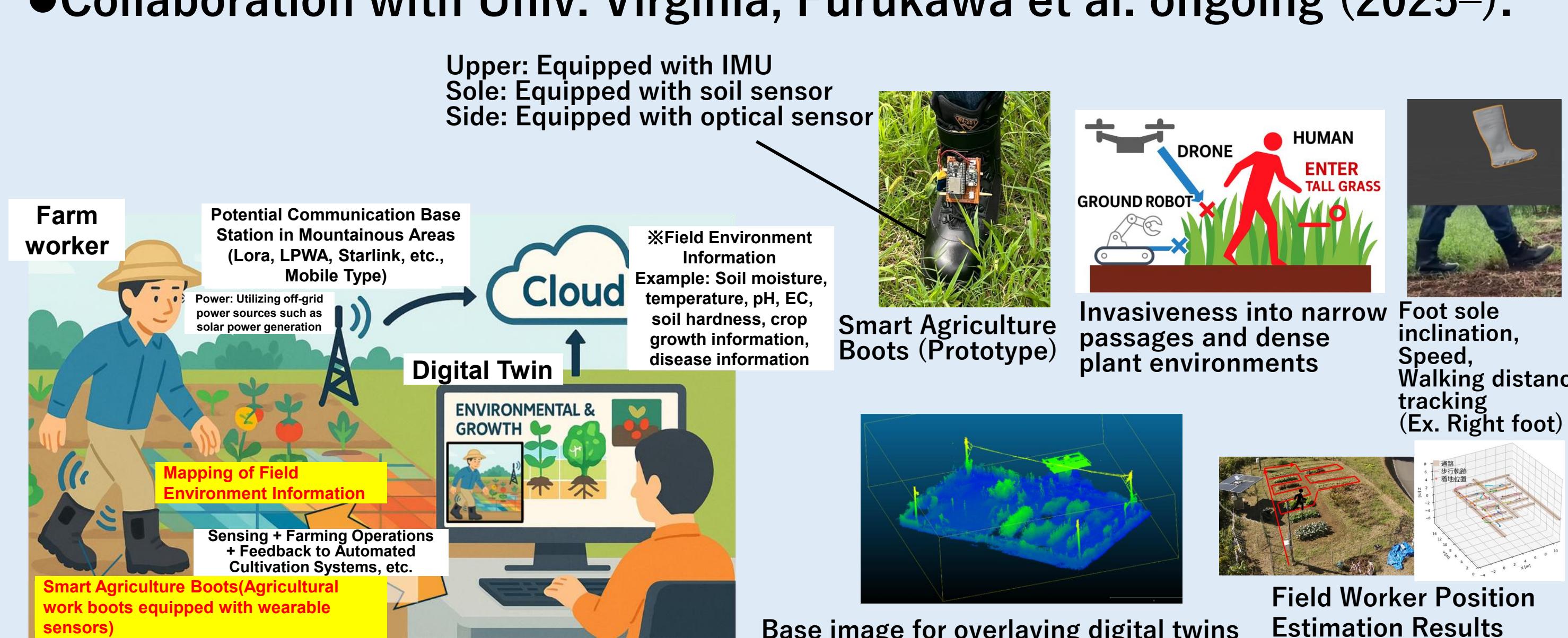
- We are collaborating with Fukatsu et al. at the National Agriculture and Food Research Organization (NARO) to develop a **robotic system that automates lower leaf removal** - a task requiring significant labor after harvesting in tomato cultivation.
- 2025–2027 Grant-in-Aid for Scientific Research (B) “Realization of a Cultivation Support Robot System Capable of Handling Work Targets Obstructed by Branches and Leaves” (Collaborator).



Technology under development

Smart Agriculture Boot Development and Digital Twin

- Using agricultural work boots equipped with **wearable sensors** (**smart agriculture boots**) to measure field environment data on the move, then integrating that data to build an agricultural digital twin with farm sensor network and other robots.
- Conceived an original approach: “**Transforming the worker themselves into a sensor platform**.”
- Achieves high-resolution, time-series environmental information mapping that complements conventional fixed sensors and remote sensing with robots, enabling labor-saving and advanced agricultural production management.
- Collaboration with Univ. Virginia, Furukawa et al. ongoing (2025–).



Environmental Information Mapping Using Smart Farming Boots for Realizing Agricultural Digital Twins

Smart Agriculture Education and Research for Realization of Super-smart Society and Creation of New Industries

Off-grid Energy & Communication System

Off-grid Power and Communications to Support Smart Agriculture

- Constructed a field (Smart Agriculture Education and Research Field) at Suzukakedai Campus, where soyabeans, cabbage, broccoli, radish, komatsuna, etc. are grown organically.
- Supplied agricultural implementation of smart agriculture in Japanese mountainous areas through Off-grid energy and communication system with solar tracking power generator panels, LEO satellite communications, and rainwater harvesting.

Concept of smart agriculture with off-grid power, communication, and water

Smart Agriculture R&E Field @ Suzukakedai Campus (Aprox. 10m x 20m = 200 m² = 2a)

Automated Agriculture robots

Off-grid power, communication, and water

by solar power power

and rainwater harvesting

by LEO satellite communication

and rainwater harvesting

by solar power power

and rainwater harvesting

by solar power power